

Status of the HRS

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CEN Bordeaux-Gradignan

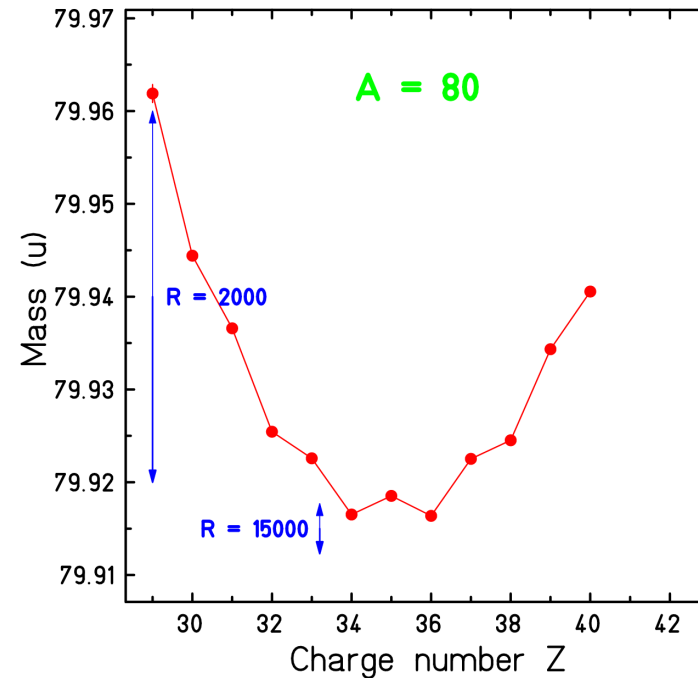
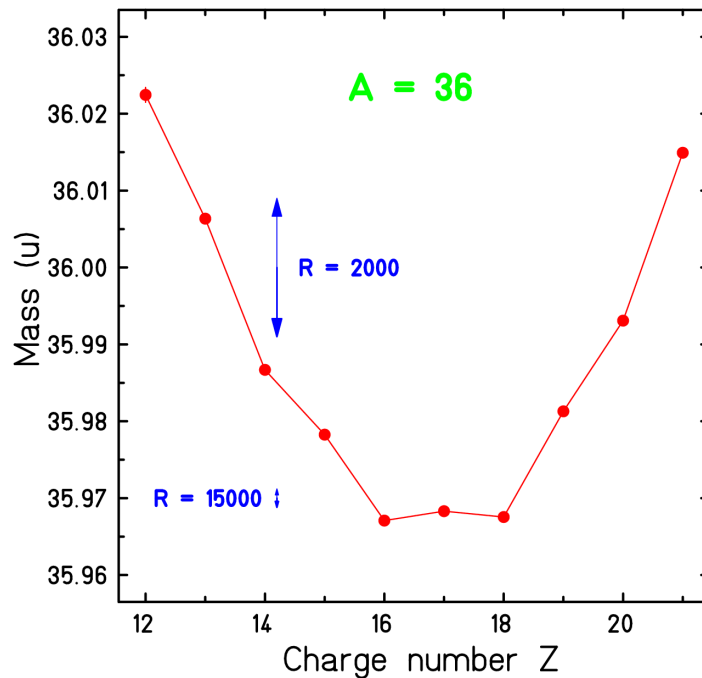
SPIRAL2-WEEK
Caen, January 28th 2010

High Resolution Separator HRS Outline

- √ HRS: Design Goal
- √ Initial Implementation
- √ New design: HRS-U180
- √ Ion optics:
 - ü COSY Infinity calculations
 - ü Optics discussion
- √ Performance study using Raytracing Turtle
- √ Summary and outlook

HRS: Design goal

High resolution separator with enough mass resolving power to allow isobaric separation.

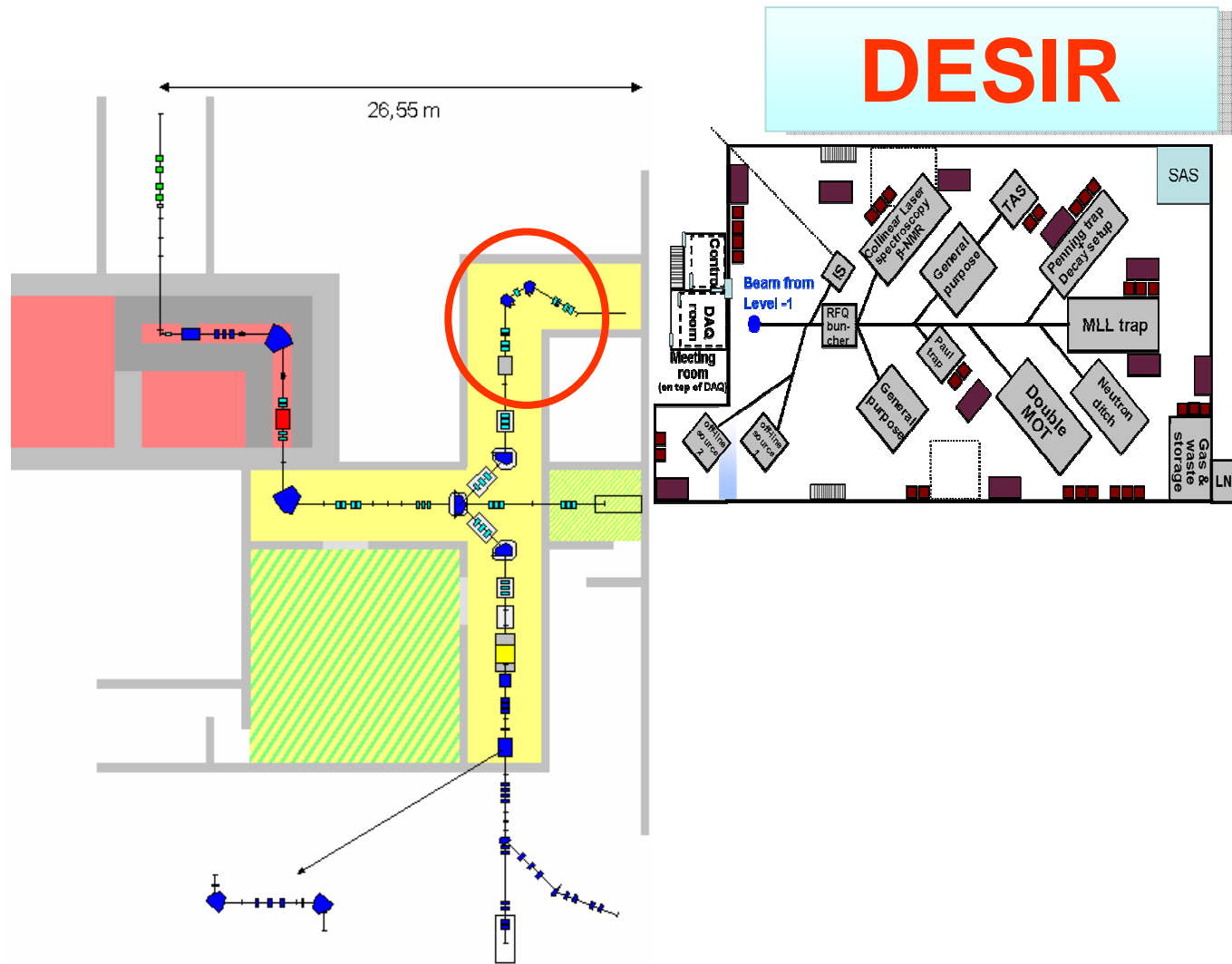


Resolving Power

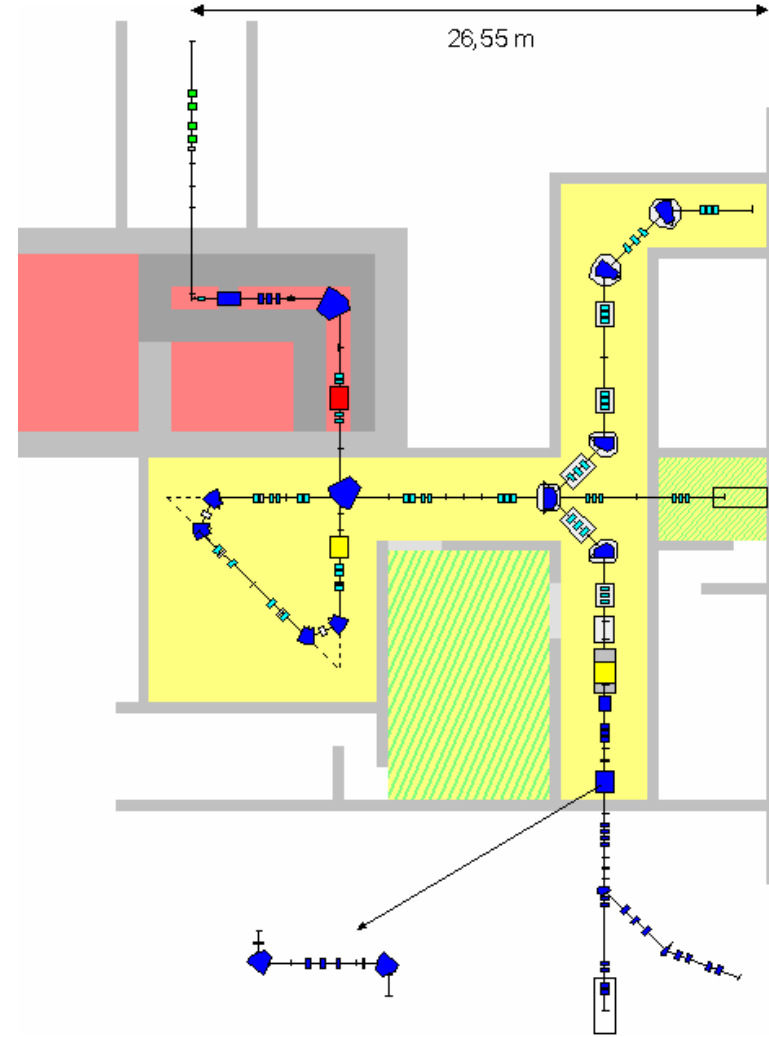
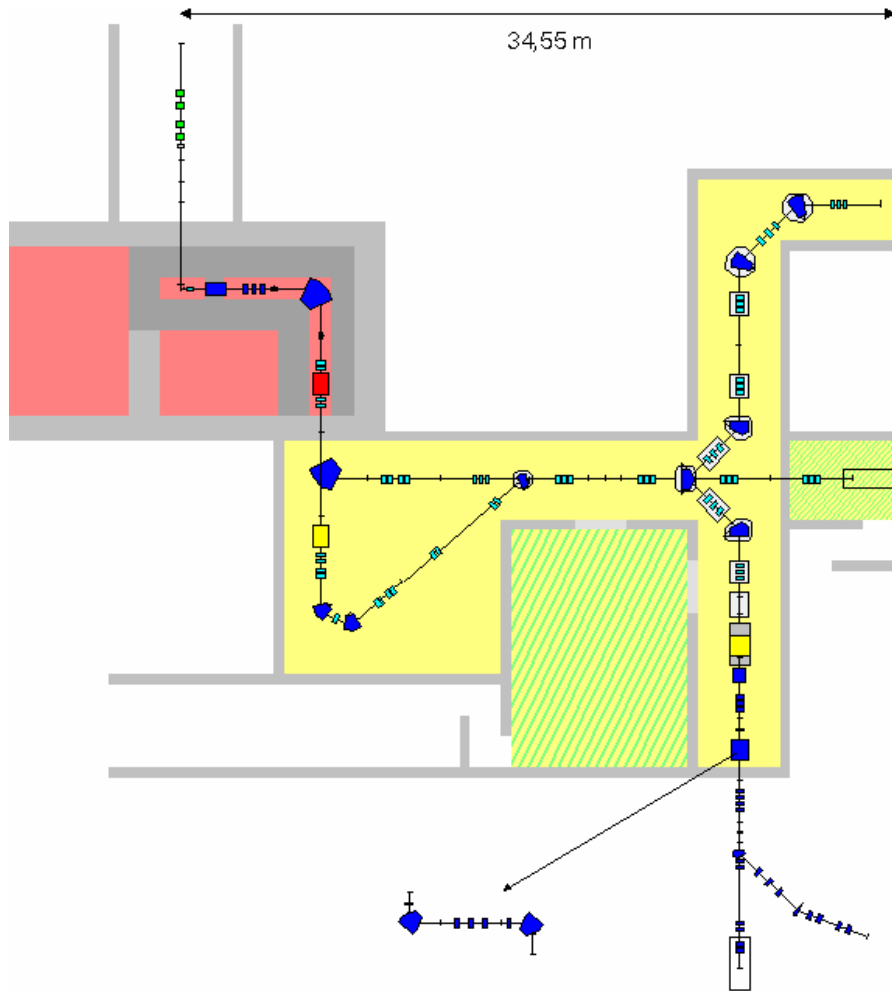
$$R = \frac{m}{\Delta m} \sim 20000$$

$$R = \frac{(x | \delta)}{2x_{00}(x | x) + \Delta}$$

HRS: initial conception



HRS: "C" and "Alpha"



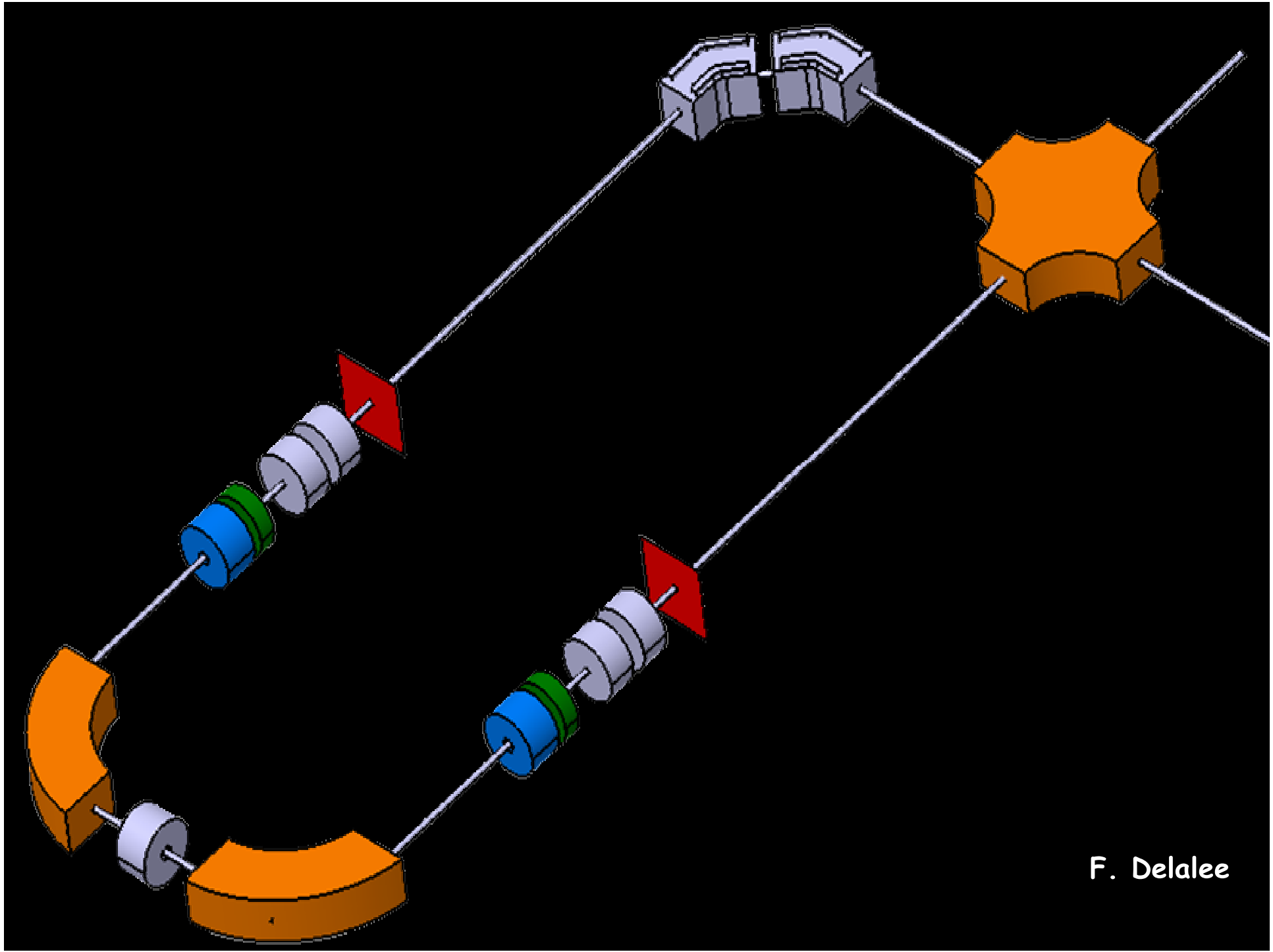
<http://www.cenbg.in2p3.fr/desir>

FIRST DESIR-HRS WORKSHOP

✓ November 12th-13th 2009, CENBG

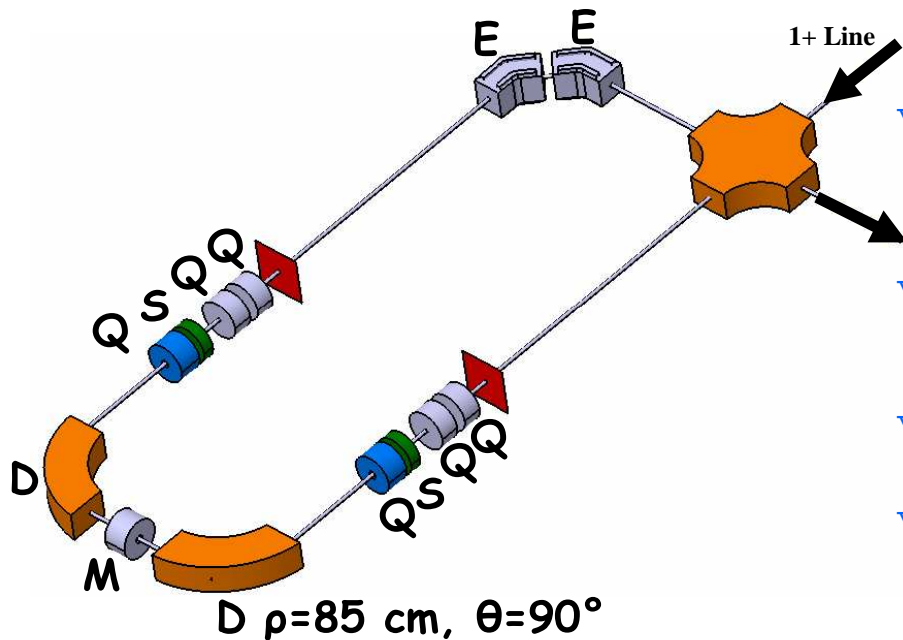
✓ Participants:

- ü Cary Davids ANL, USA
- ü Rich Baartman TRIUMF, Canada
- ü Helmut Weick, GSI, Germany
- ü François Méot, Grenoble, France
- ü Maurice Duval, GANIL, France
- ü Franck Varenne, GANIL, France
- ü David Lunney, CSNSM, France
- ü DESIR-HRS Bordeaux Team



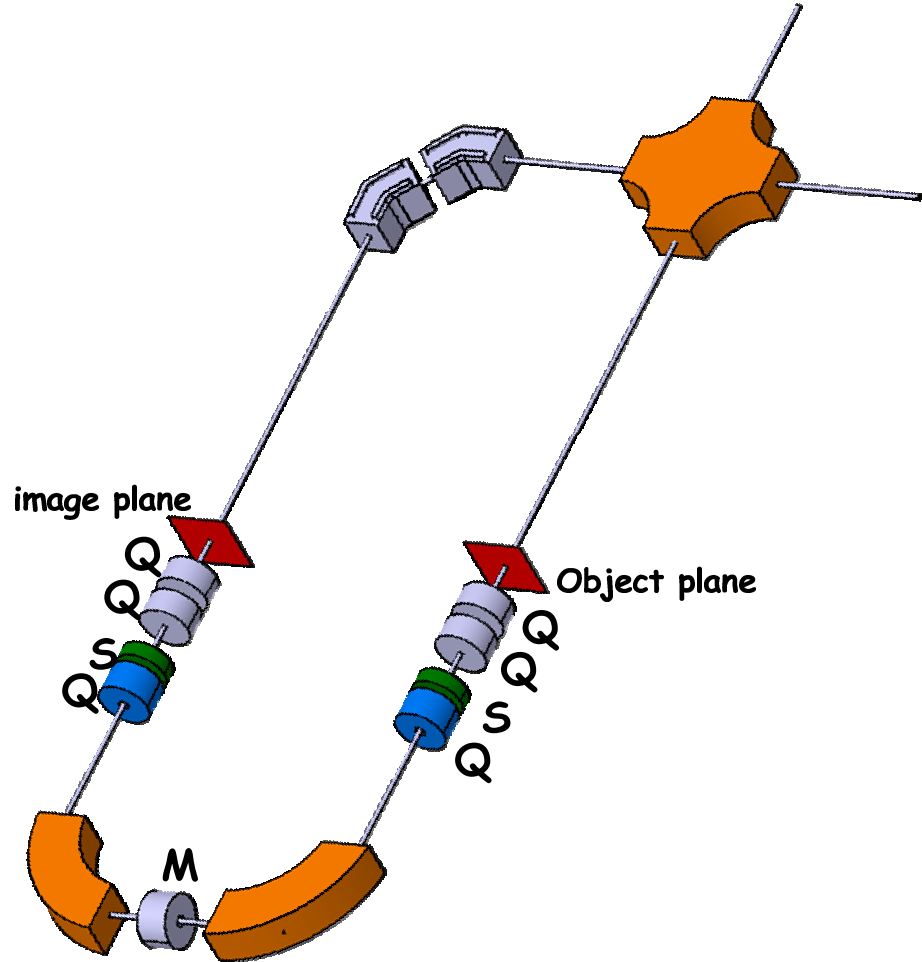
F. Delalee

HRS: "U180"



- ✓ The quadrupole doublet matching section produces a ribbon-shaped beam, so y -angles are small, minimizing b aberrations
- ✓ The first quadrupole diverges in x and converges in y , giving a small y size which minimizes y aberrations
- ✓ The large x area in the magnets gives mass dispersion
- ✓ Focus conditions in centre: $(a/a)=(y/b)=(b/y)=0$
- ✓ The reverse matching section transforms the ribbon-shaped beam back to a circular cross-section, allowing a 1 mm x -selection slit at the focal plane
- ✓ The 2 sextupoles and 1 multipole to correct aberrations to 5th order
- ✓ The two electrical benders transport the beam back to the 1+ Line

HRS U180



Transfer matrix

	(x,)	(a,)	(y,)	(b,)
x	-1.0	-4.5	0.0	0.0
a	0.3E-7	-1.0	0.0	0.0
y	0.0	0.0	1.0	23.2
b	0.0	0.0	-0.2E-7	1.0
δm	-31.5	-70.9	0.0	0.0

$\ddot{u} \ (x|\delta) = -31.5 \text{ cm/\%}$

\ddot{u} Mirror symmetric

\ddot{u} point-to-point both x and y

$R \sim 31000$

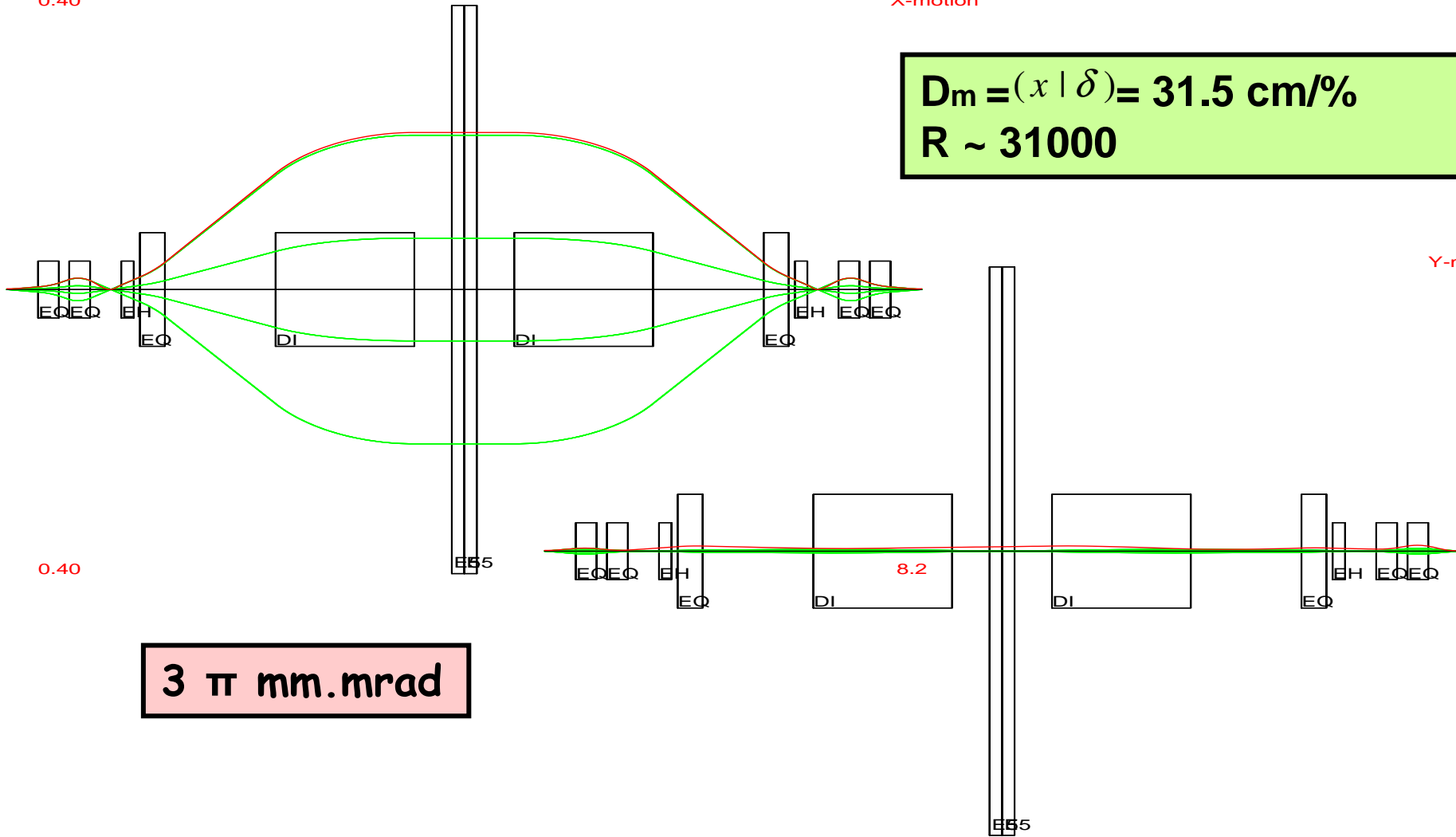
COSY INFINITY X and Y motion

0.40

X-motion

$$D_m = (x | \delta) = 31.5 \text{ cm/\%}$$

$$R \sim 31000$$



Y-motion

0.40

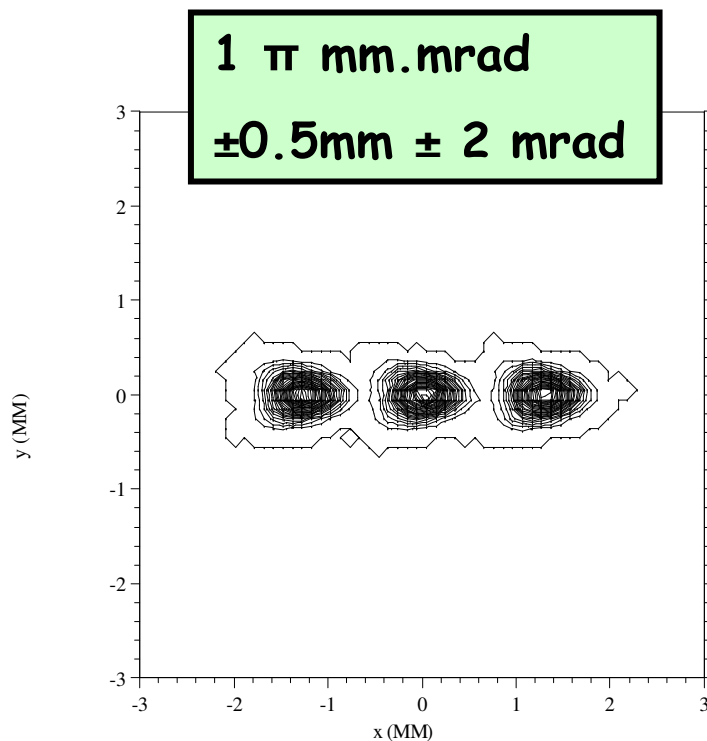
3 π mm.mrad

Ion optics discussion

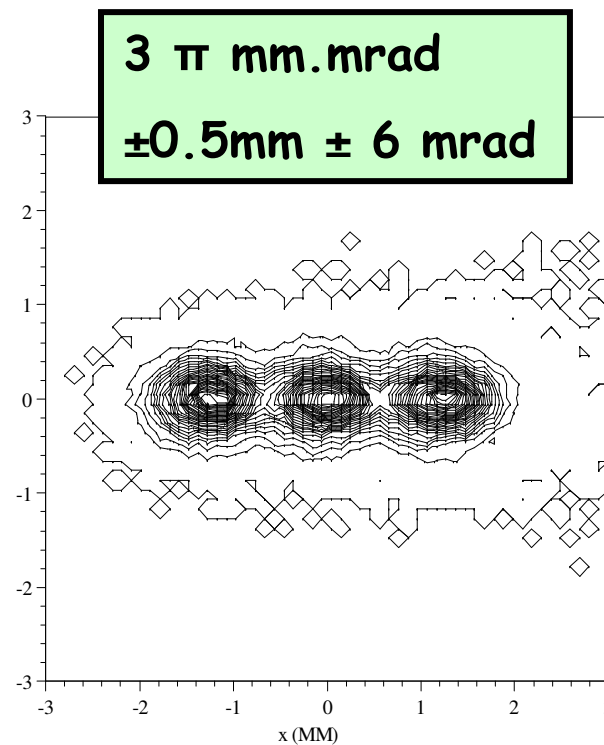
- ✓ Symmetric design helps to minimize aberrations.
- ✓ Large mass dispersion ($x|\delta$) and small aberration coefficients are obtained by increasing the incident and exit angles at the boundary of a magnetic sector.
 - ü 36.5° was chosen for the 90° bending dipoles
- ✓ Quadrupoles are used as the focusing mode in the y -direction and the defocusing mode in the x -direction.
 - ü By choosing suitable distances and fitting the quadrupole strengths, a beam profile in the dipole gap can be made very wide in the x -direction and narrow in the y -direction, attaining two advantages simultaneously:
 - * High transmission
 - * Small image magnification ($x|x$) to attain high resolution

Performance study using Raytracing Turtle

X-Y phase space for isobars with mass deviations
-1/20000, 0, +1/20000



97% transmission in 1 mm²
0.09% cross-contamination



77% transmission 1 mm²
1.4% cross-contamination

Laurent Serani

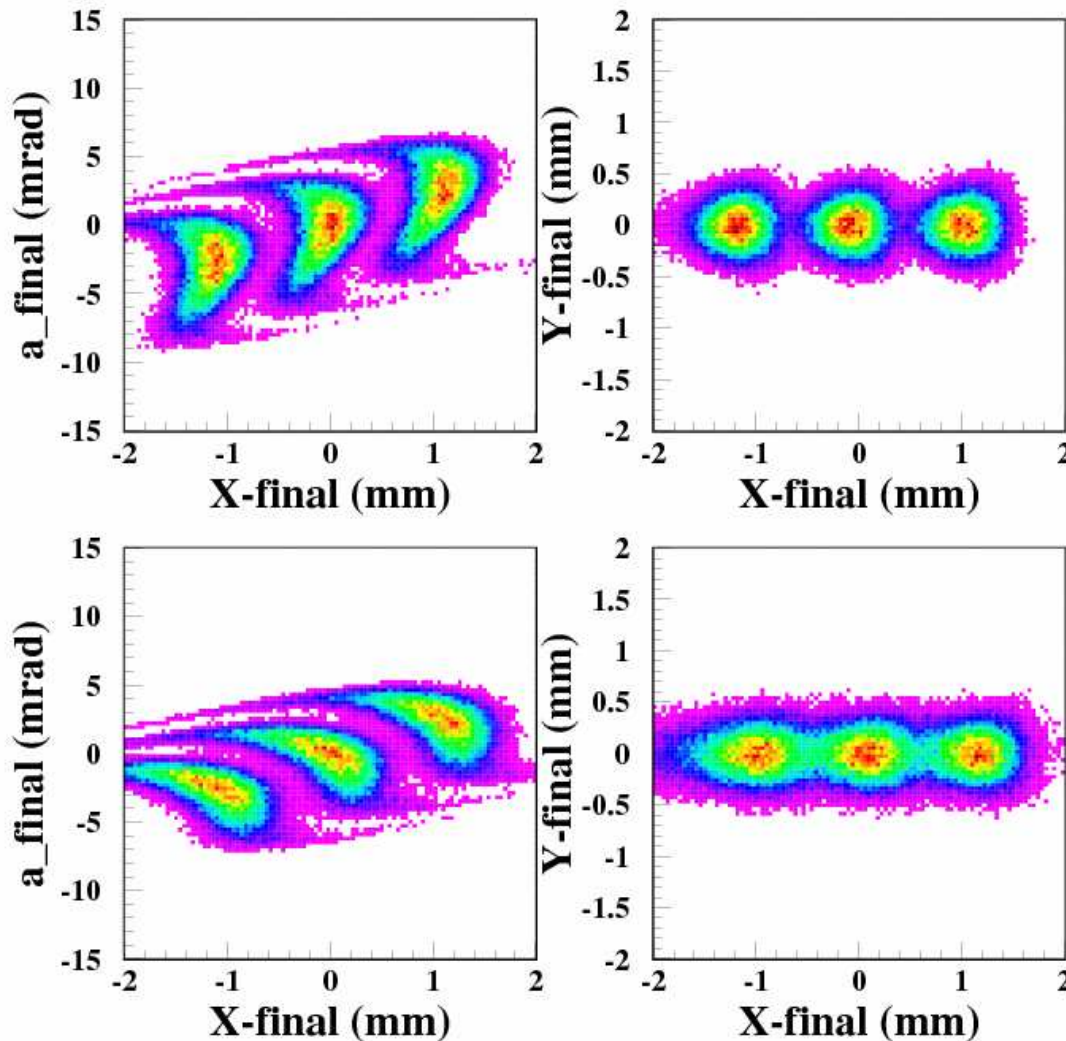
Cost Estimation

The Cost Estimation is shown in the following table:

concept	number	total cost (€)
Dipole	2	388.744,08
Long quadrupoles	4	278.121,03
Short quadrupoles	2	156.636,31
Sextupoles	2	100.533,15
Multipoles	1	66.481,58
Vacuum chambers	3	92.087,15
Vacuum system	1	130.200,00
Electrostatic correctors	1	56.875,00
Power sources	6	302.709,33
TOTAL VAT EXCLUDED		1.572.387,63

Prices include conceptual design, manufacturing design and manufacturing. Turnkey

Misalignment effects on mass resolution



Phase spaces calculated to 5th order

50000 particles with mass deviations
-1/20000, 0, +1/20000

A shift in the multipole of 0.2 mm in
the x -direction induces a deformation
in the x - a phase space which is
responsible for the blur in the final
mass separation.

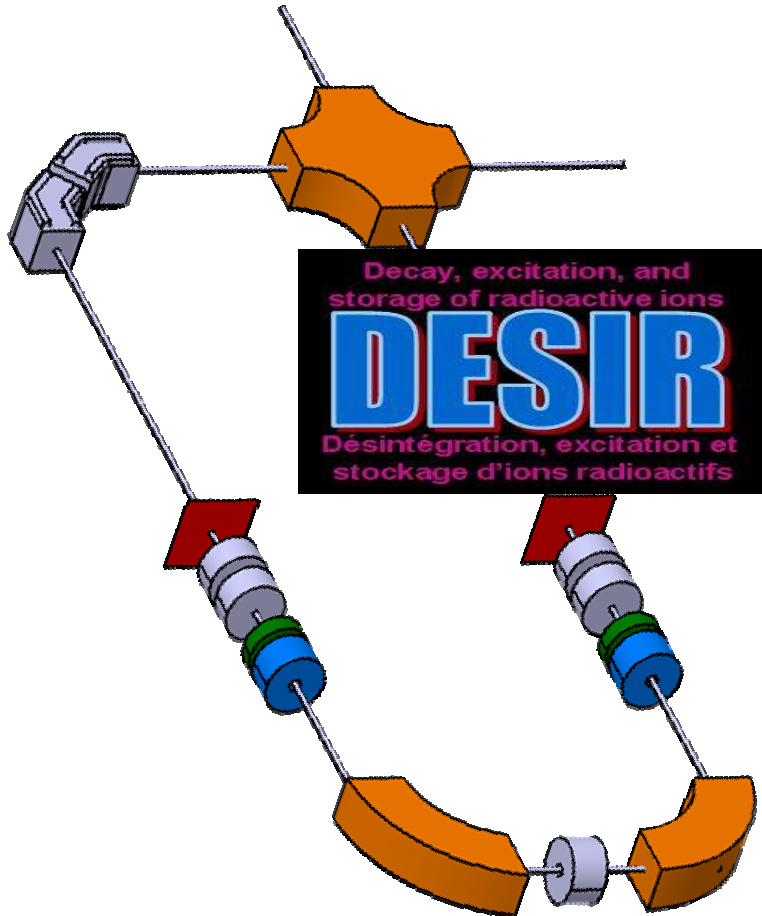
Summary

- ∇ A new ion-optical design concept for the HRS, the HRS-U180, is currently under study as a result of the discussion with experts at the First HRS Workshop held at CENBG last November.
- ∇ This design gives a compact configuration, high transmission and high resolving power, providing monoisotopic beams of exotic nuclides.
- ∇ This compact configuration is less expensive, concerning both installation and operation costs.
- ∇ A beam emittance of the order of $<3 \pi$ mm mrad and an energy dispersion of about 1 eV are needed. These requirements will be fulfilled with the RFQ cooler SHIRAC.

Next steps

- ✓ By the end of the next week the specifications for the dipole magnets will be sent to M. Duval who will calculate the corresponding 3D TOSCA maps.
- ✓ We estimate to have this calculations ready by the end of February and start the raytracing evaluation to study the performance of the system.
- ✓ End of march: first document on the definition of the size envelope of the HRS.
- ✓ October: we expect to have the final design.
- ✓ End of 2010 Technical Specifications finished. Order dipole magnets 2011.
- ✓ Beginning of 2013 mounting and test of the HRS at Bordeaux.

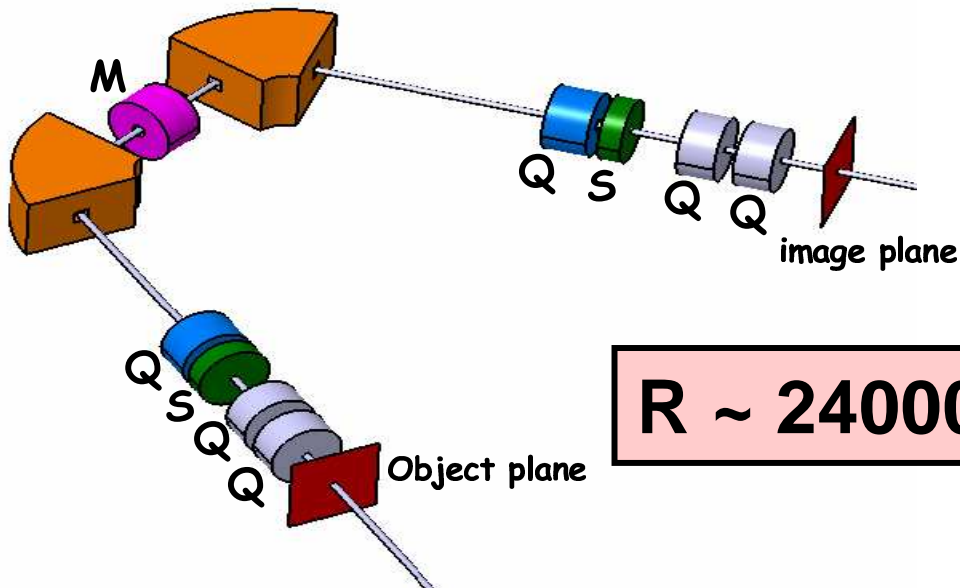
DESIR-HRS working group @CENBG



- ü Blank, Bertram
- ü Delalée, Franck
- ü Kurtukian-Nieto, Teresa
- ü Serani, Laurent

Backup slides

HRS C135



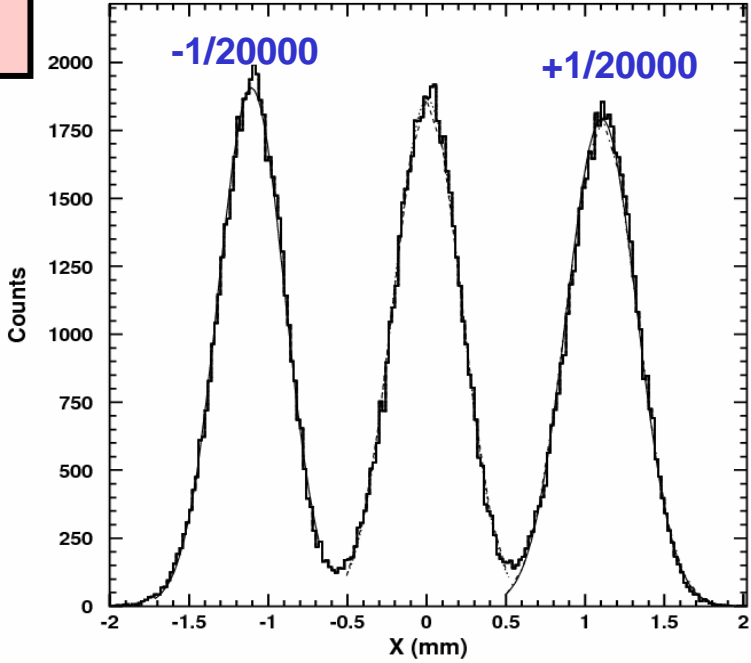
$\ddot{u} \ (x|\delta) = -24 \text{ cm}/\%$

\ddot{u} Mirror symmetric

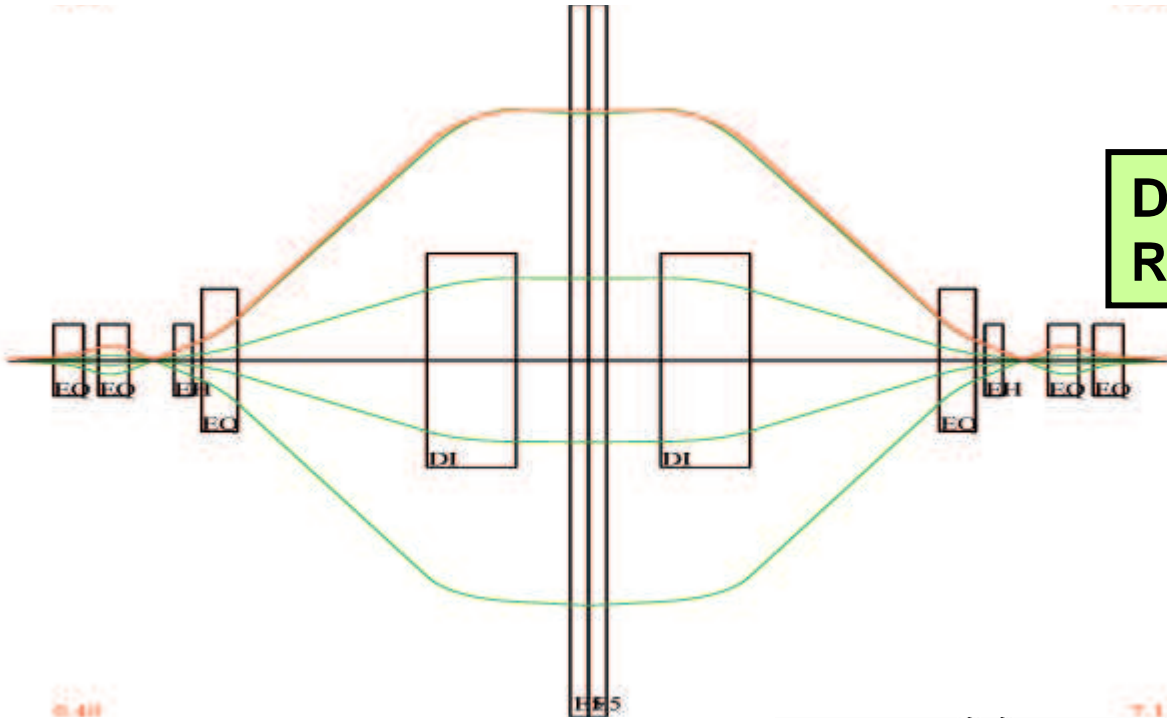
\ddot{u} point-to-point both x and y

R ~ 24000

Transfer matrix				
	(x,)	(a,)	(y,)	(b,)
x	-1.0000	-4.5202	0.0000	0.0000
a	0.28E-7	-0.9999	0.0000	0.0000
y	0.0000	0.0000	1.0000	0.25E-7
b	0.0000	0.0000	-0.12E-8	1.0000
δm	-24.10	-54.47	0.0000	0.0000

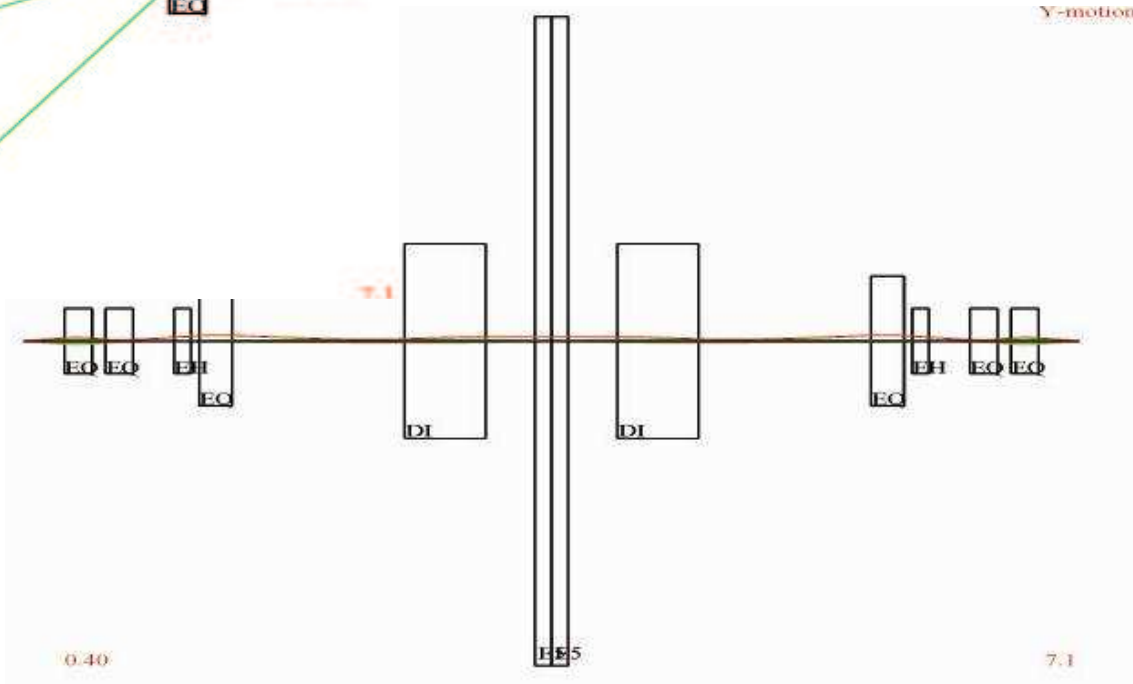


COSY INFINITY X and Y motion

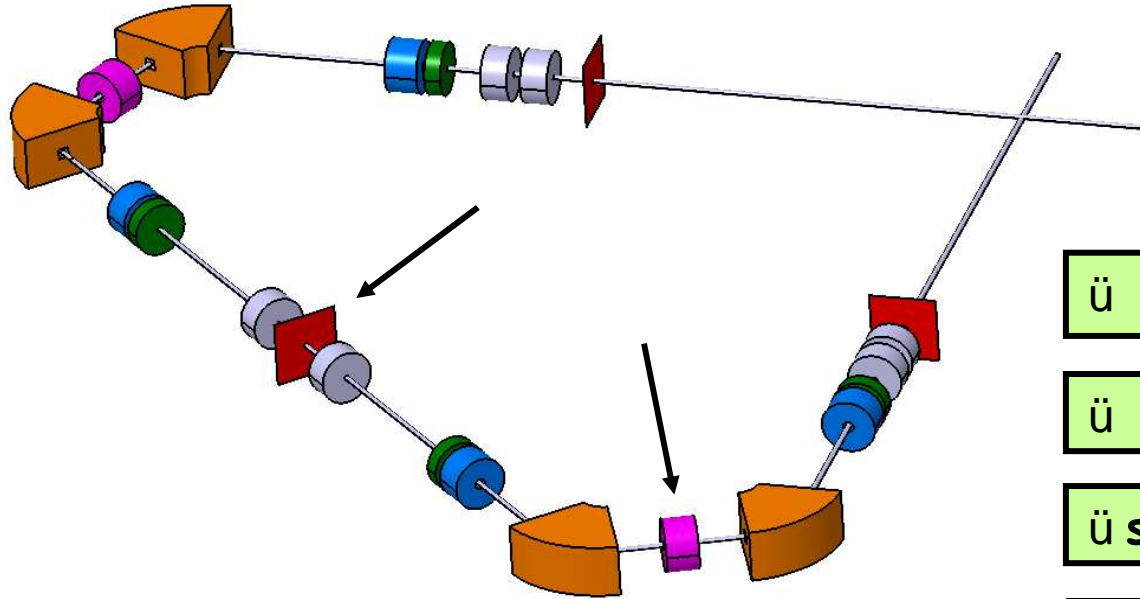


$D_m = (x | \delta) = 24.10 \text{ cm/\%}$
 $R \sim 24000$

$3 \pi \text{ mm.mrad}$



HRS Alpha Asymmetric: short



$$\ddot{u} (x|\delta m) \sim 9 \text{ cm/\%}$$

\ddot{u} asymmetric for M plane

\ddot{u} symmetric for mid-plane

$$\ddot{u} (x|x) \sim 0.4$$

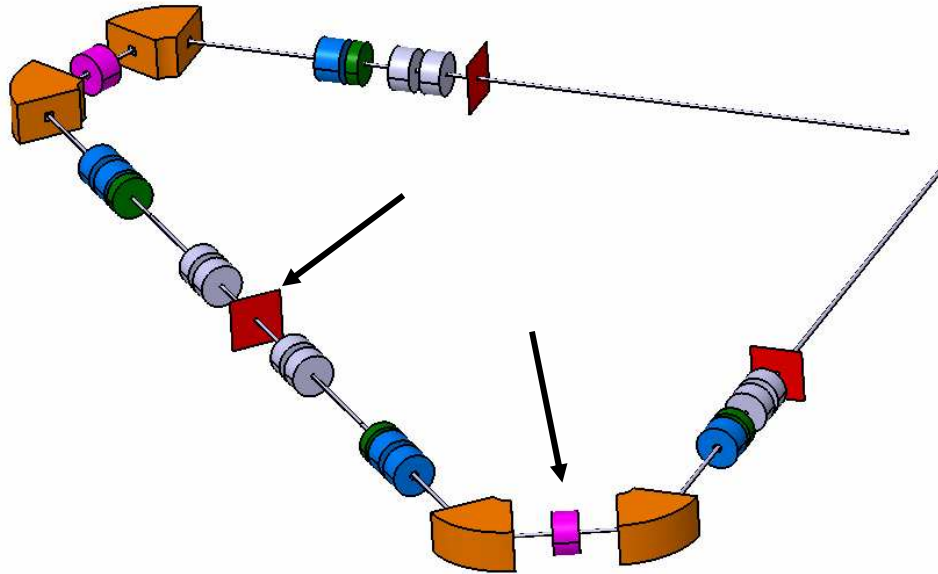
\ddot{u} point-to-point both x and y

Transfer matrix :

	(x,)	(a,)	(y,)	(b,)
x	0.4004	5.9434	0.0000	0.0000
a	0.10E-6	2.4972	0.0000	0.0000
y	0.0000	0.0000	1.7245	4.5850
b	0.0000	0.0000	-0.53E-7	0.5799
δm	8.66	-0.13E-6	0.0000	0.0000

$$R \sim 21750$$

HRS Alpha Asymmetric: Large



$\ddot{u} (x|\delta m) \sim 10 \text{ cm}/\%$

\ddot{u} asymmetric for M plane

\ddot{u} symmetric for mid-plane

$\ddot{u} (x|x) \sim 0.4$

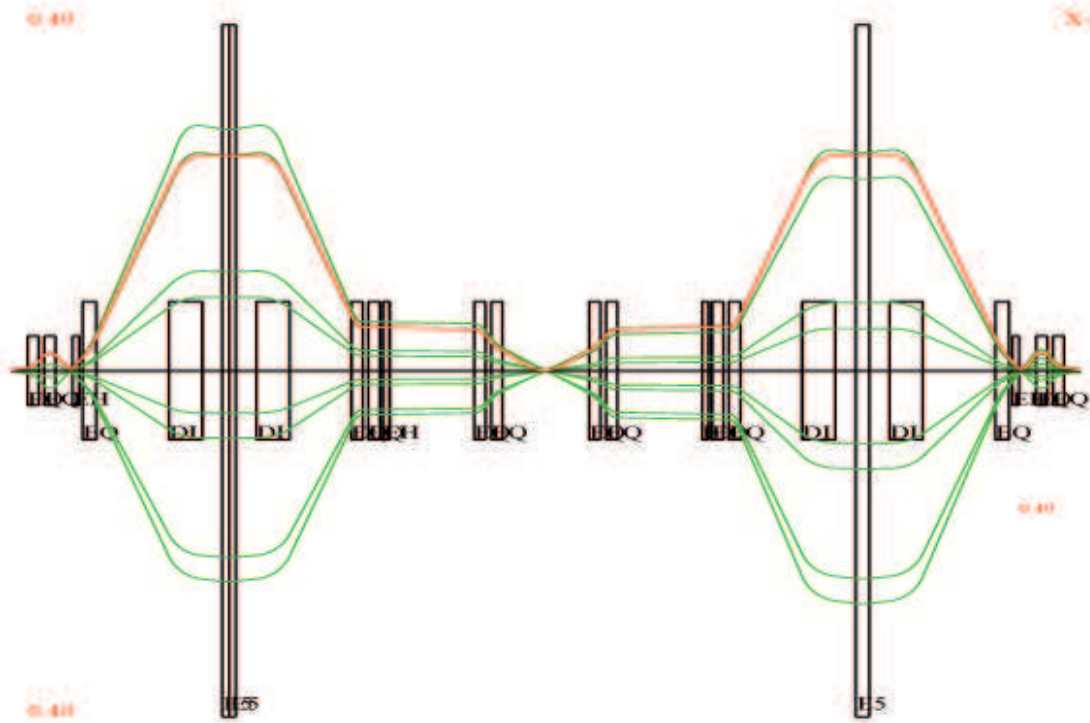
\ddot{u} point-to-point in x

Transfer matrix :

	(x,)	(a,)	(y,)	(b,)
x	0.4043	5.8394	0.0000	0.0000
a	-0.53E-7	2.4732	0.0000	0.0000
y	0.0000	0.0000	26.19	-0.2400
b	0.0000	0.0000	4.1672	-0.16E-10
δm	10.23	0.49E-8	0.0000	0.0000

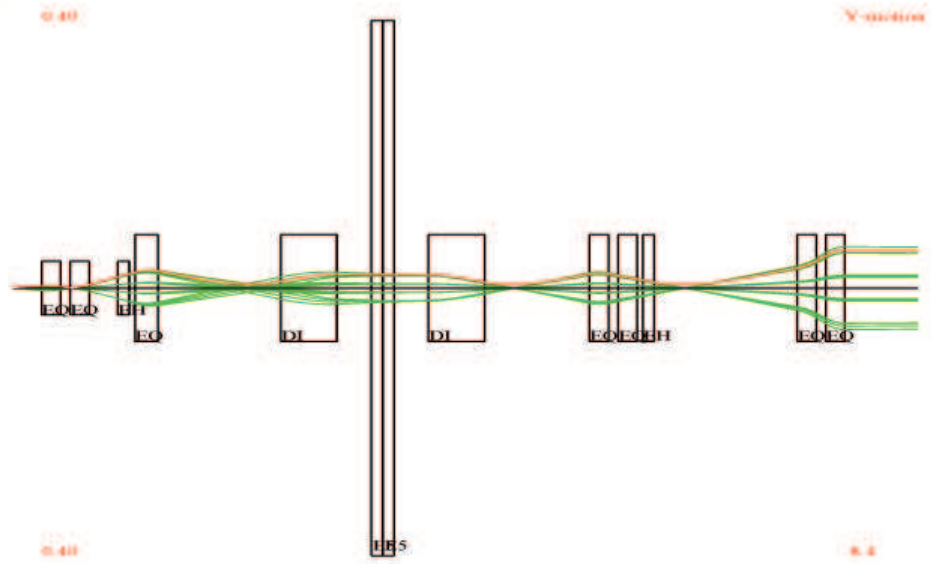
$R \sim 25500$

COSY INFINITY X and Y motion



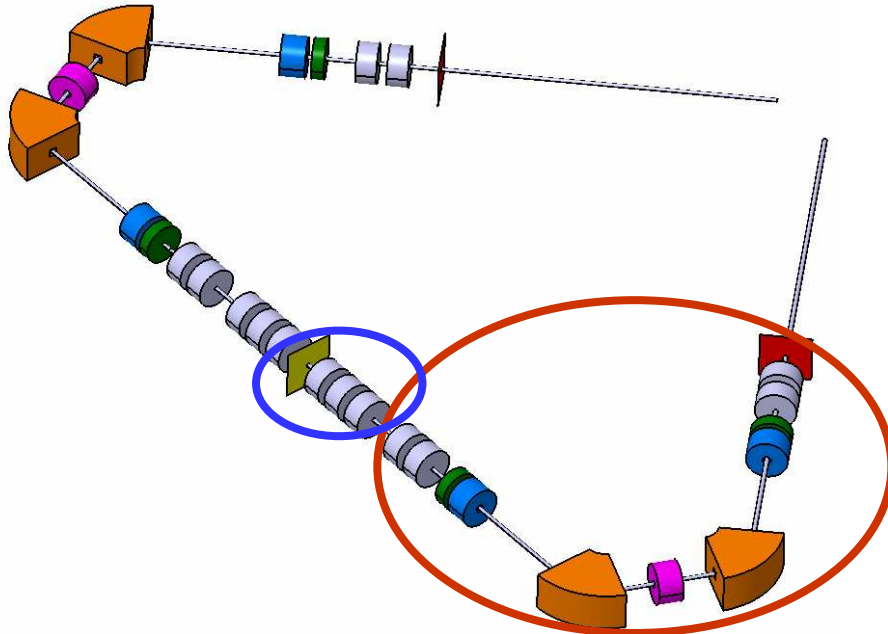
X-motion

$D_m = (x | \delta) \sim 10 \text{ cm/\%}$
 $R \sim 25500$



Y-motion

HRS Alpha Symmetric



ü Same as HRS C135

ü Compensation triplet

ü Doubly symmetric

R ~ 24000

Transfer matrix

	(x,)	(a,)	(y,)	(b,)
x	-1.0000	-4.5202	0.0000	0.0000
a	0.28E-7	-0.9999	0.0000	0.0000
y	0.0000	0.0000	1.0000	0.25E-7
b	0.0000	0.0000	-0.12E-8	1.0000
δm	-24.10	-54.47	0.0000	0.0000

Transfer matrix

	(x,)	(a,)	(y,)	(b,)
x	0.3787	-5.9685	0.0000	0.0000
a	-0.11E-7	2.6407	0.0000	0.0000
y	0.0000	0.0000	-0.8472	-4.3693
b	0.0000	0.0000	0.2289	0.38E-6
δm	9.1254	0.34E-5	0.0000	0.0000